

Generalized Graph Signal Processing

Feng Ji Wee Peng Tay

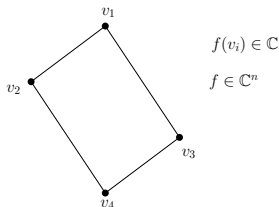
Nanyang Technological University

November 2019



Graph signal processing

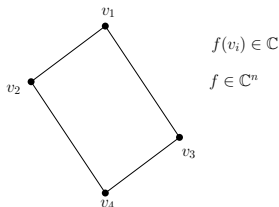
- Signal f on a graph $G = (V, E)$: $f : V \mapsto \mathbb{C}$



- Examples: sensor networks, social networks, transportation networks, ...
- Exploits the underlying graph structure (correlations between nodes) to perform signal processing and inference.

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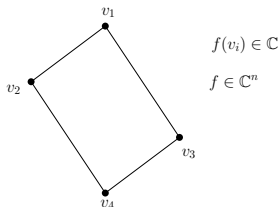


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- Main idea: represent f using basis Φ associated with graph shift operator $A_G = \Phi \Lambda \Phi^*$ (adjacency, Laplacian, etc. that captures the local graph structure).

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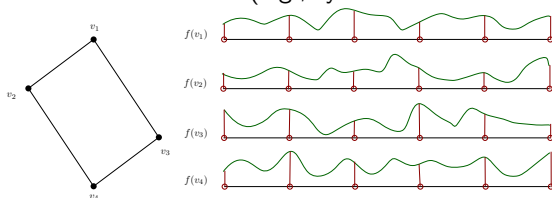
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$$\text{GFT: } \hat{f} = \Phi^* f \stackrel{[1]}{=} (\langle f, \phi \rangle_{\mathbb{C}^n})_{\phi \in \Phi}$$

[1] B. Girault, A. Ortega, and S. S. Narayanan, "Irregularity-aware graph Fourier transforms," *IEEE Transactions on Signal Processing*, vol. 66, no. 21, pp. 5746–5761, Nov. 2018.

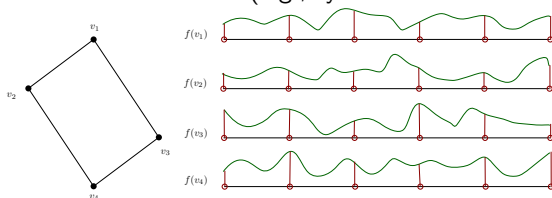
Time-vertex GSP

- [2]: $f(v, \cdot) \in \mathbb{C}^T$ for each $v \in V$, $T < \infty$, is a **discrete time series** with **common time indices** (e.g., synchronous uniform sampling at every vertex).



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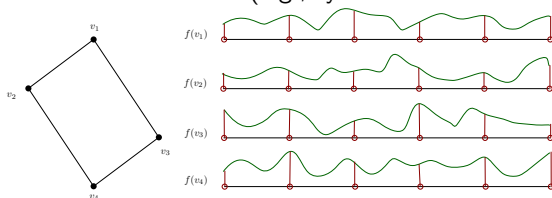
- For each $v \in V$, can apply DFT on $f(v, \cdot)$:

$$\text{DFT}(f(v, \cdot)) = \Xi^* \text{vec}(f(v, \cdot)),$$

where Ξ^* is the DFT matrix.

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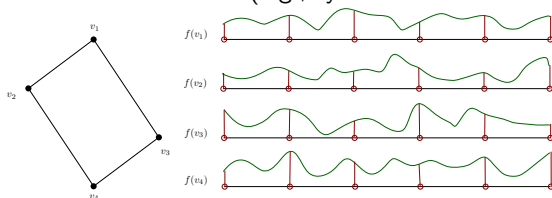
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- Joint time-vertex Fourier transform: view $f = (f(v, t))$ as a matrix,

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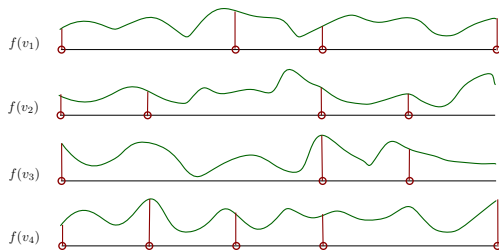
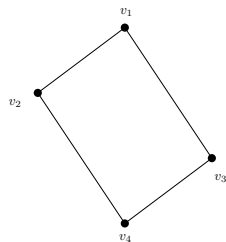
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- A representation in the basis $\Phi \otimes \Xi$.

[2] F. Grassi, A. Loukas, N. Perraudin, and B. Ricaud, "A time-vertex signal processing framework: Scalable processing and meaningful representations for time-series on graphs," *IEEE Trans. Signal Process.*, vol. 66, no. 3, pp. 817–829, Feb. 2018.

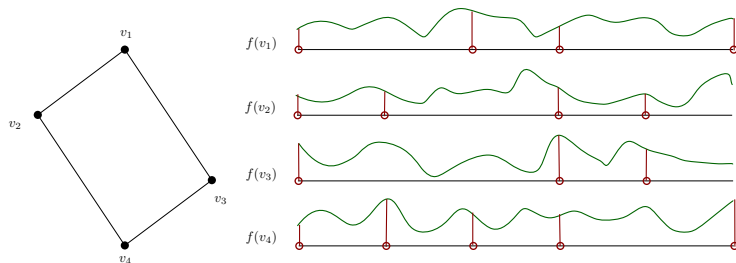
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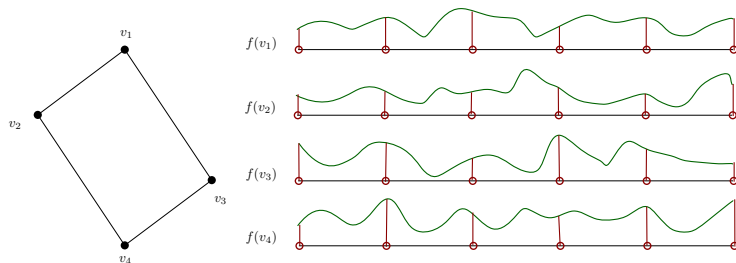
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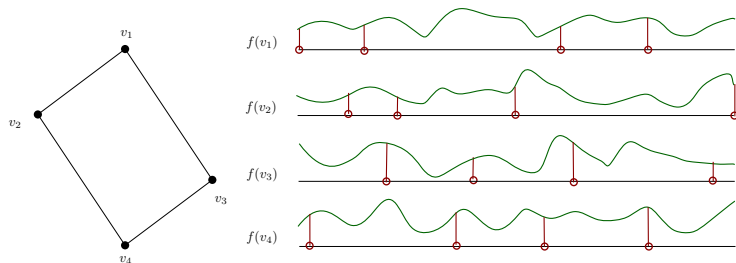
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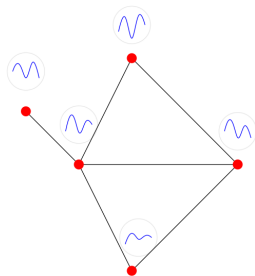
Time-vertex GSP

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- If vertex domain dimension = 2, can reconstruct.
- However, asynchronous sampling (e.g., sensor networks) ... now impossible to reconstruct the signal.



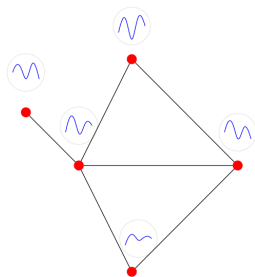
Generalized GSP

- Signal at each vertex is from an infinite dimensional separable Hilbert space $\mathcal{H} = L^2(\Omega, \mu)$.



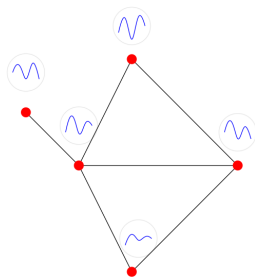
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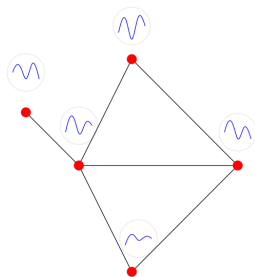
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- Non-synchronous sampling (time indices are not same for different vertices).
- Allows **joint** modeling of $f(v, x)$ over $v \in V$, $x \in \mathcal{H}$.



The rest of this talk...

- 1 Generalized Graph Signals and \mathcal{F} -Transform
- 2 Sampling Theorem
- 3 Filtering
- 4 Conclusion

Details in

F. Ji and W. P. Tay, "A Hilbert space theory of generalized graph signal processing," *IEEE Trans. Signal Process.*, 2019, accepted. [Online]. Available: <https://arxiv.org/abs/1904.11655>.

Outline

- 1 Generalized Graph Signals and \mathcal{F} -Transform
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Tensor product space

- Tensor product $\mathbb{C}^n \otimes \mathcal{H} = \left\{ \sum_{i=1}^n v_i \otimes h_i \right\}$ with
 - Ⓐ $v_1 \otimes h + v_2 \otimes h = (v_1 + v_2) \otimes h$;
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- Generalized graph signal $f : V \mapsto \mathcal{H}$. $S(G, \mathcal{H})$ - space of graph signals in \mathcal{H} .

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Lemma

$S(G, \mathcal{H})$ is a *Hilbert space* isomorphic to $\mathbb{C}^n \otimes \mathcal{H}, |V| = n.$

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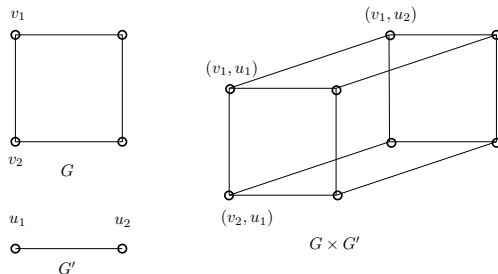
- $f = \sum_{\phi \otimes \xi} \mathcal{F}_f(\phi \otimes \xi) \cdot \phi \otimes \xi$

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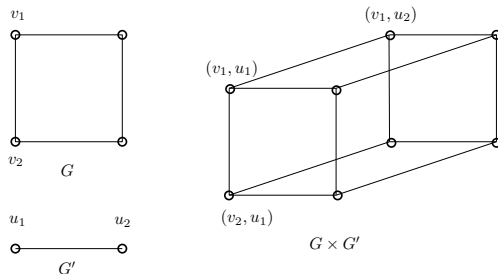
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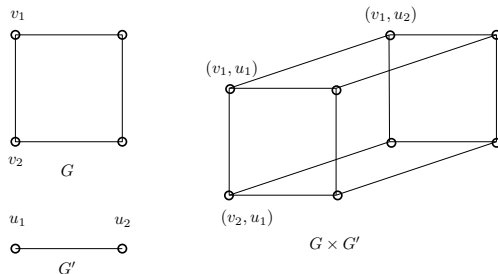
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 - ▶ $G' = \text{path graph}$: \mathcal{F} -transform = TV-transform



Example of infinite dimensional \mathcal{H}

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- Fredholm operator

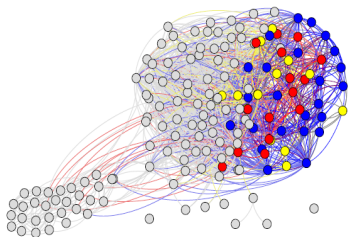
$$Af(x) = \int_{\Omega} K(x, y)f(y)d\mu(y),$$

Hermitian $K \in L^2(\Omega \times \Omega) \implies A$ compact, self-adjoint.

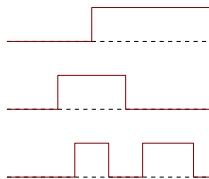
Choose different kernels for different applications.

Spectral analysis example

- Information propagation over a network: SI, SIR, SIRS

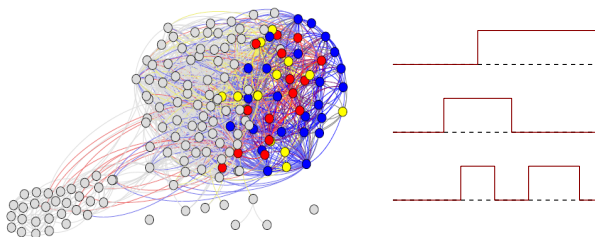


Source: J. McAuley and J. Leskovec. Learning to Discover Social Circles in Ego Networks. NIPS, 2012



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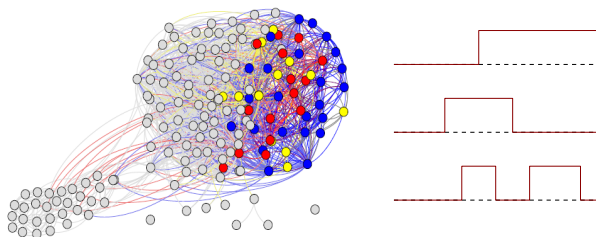


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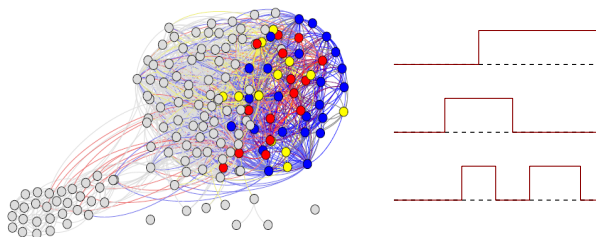


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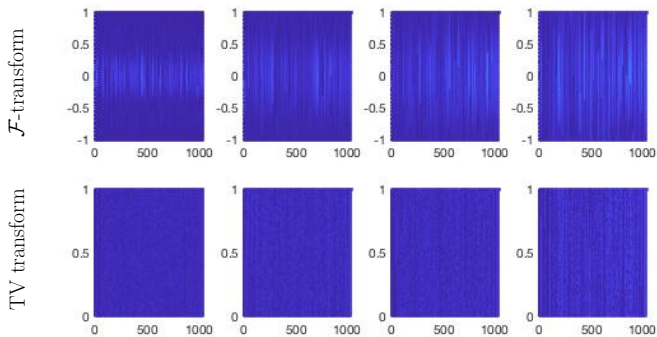
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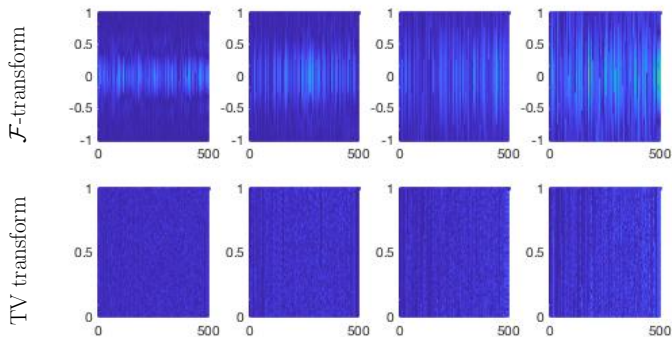
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- Suppose infection rate $\lambda_I = 1$, what is the recovery rate λ_R ?
- Loss of information in using
 - GSP (aggregated statistics over time) or
 - TV-GSP (uniform sampling over time).

Spectral analysis example



Facebook network, $\lambda_I = 1$: $\lambda_R = 0$, $\lambda_R = 1/5$, $\lambda_R = 1/2$ and $\lambda_R = 1$.

Spectral analysis example



Enron email network, $\lambda_I = 1$: $\lambda_R = 0$, $\lambda_R = 1/5$, $\lambda_R = 1/2$ and $\lambda_R = 1$.

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Asynchronous joint sampling

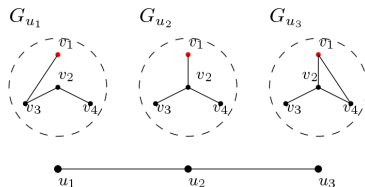
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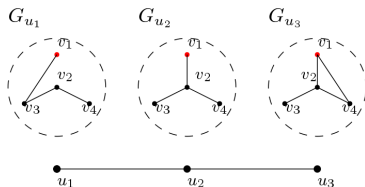
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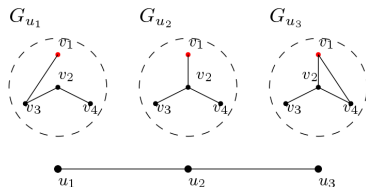
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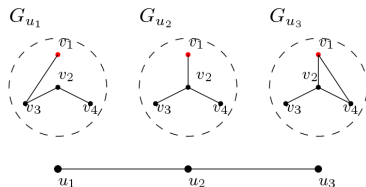
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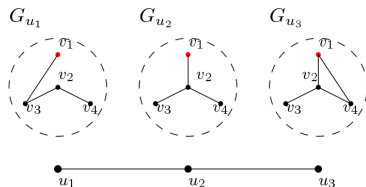
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- **“Reconstructible vertex set”:** can reconstruct whole graph signal at each instant $x \in \Omega$ from signals in this set. \implies linearly independent rows of matrix Φ' .

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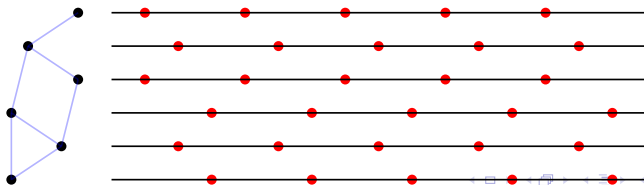
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- But if $\{f(v, \cdot) : v \in V\}$ is bandlimited in graph vertex domain, then only need $\approx 2B/\delta(\Phi')$ for each vertex to recover all signals.

Sampling example

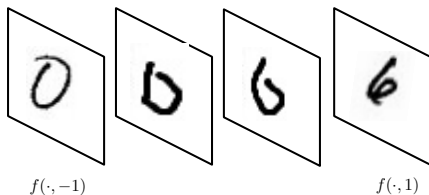
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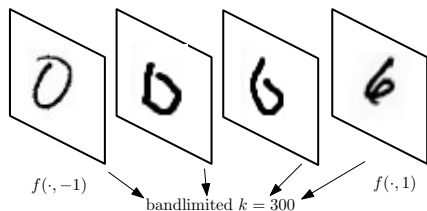
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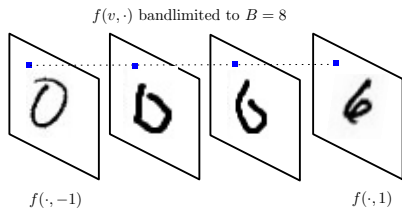
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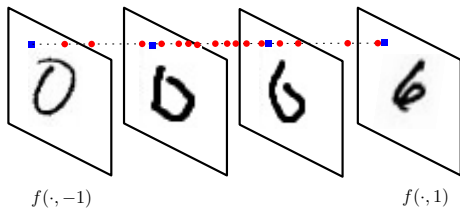
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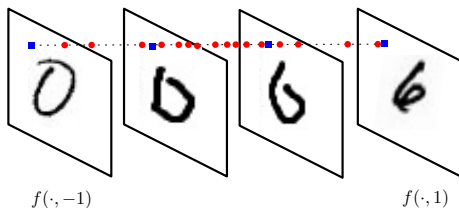
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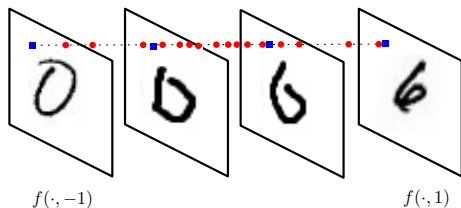
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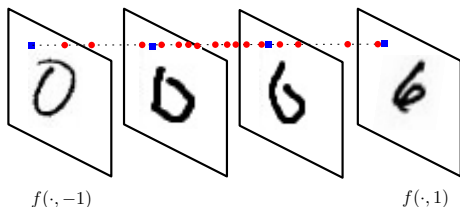
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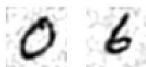
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Outline

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- 2 Sampling Theorem
- 3 Filtering**
- 4 Conclusion

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If finite dimensional, J is polynomial $\therefore \exists$ minimal polynomial.

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- If $m_\lambda(A_G) = 1$, traditional GSP: all shift invariant filters are polynomial.
Not true in GGSP even if $m_\lambda(A_G \otimes A) = 1$ [e.g., $L = A_G \otimes J$].

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 - 3 Self-adjoint L : *weakly shift invariant* \iff *shift invariant*.
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 - Not always true, but almost always in practice ...

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- G has at least 3 nodes.
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- If A_G is the Laplacian matrix, we can restrict to the orthogonal complement of 0-eigenspace of $A_G \otimes A$.

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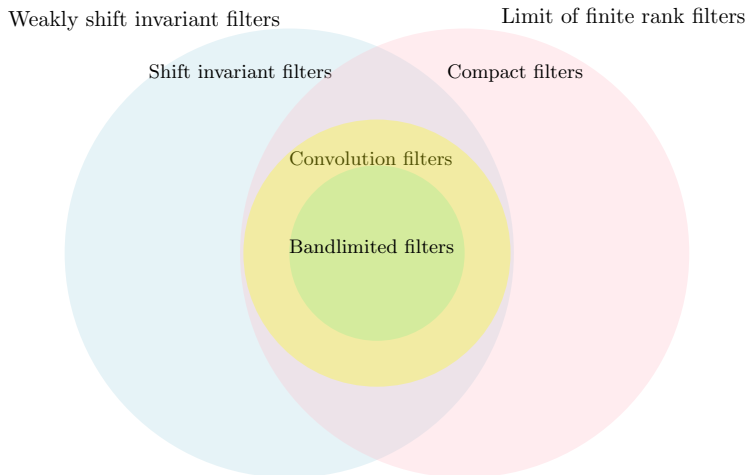
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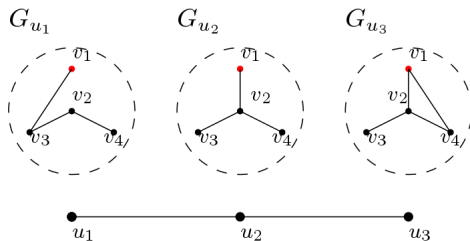
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- Polynomial filter $P(A_G \otimes A)$ with $a_0 \neq 0$ is non-compact, therefore not convolution.

Different classes of filters

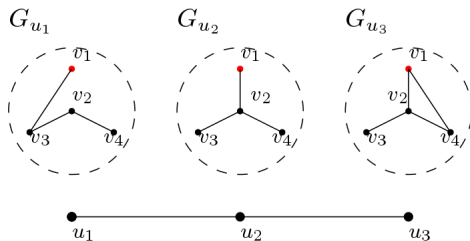


Adaptive polynomial filters



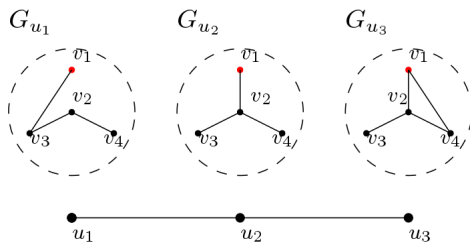
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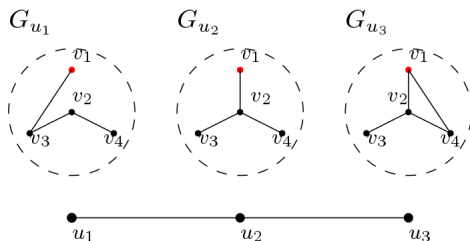
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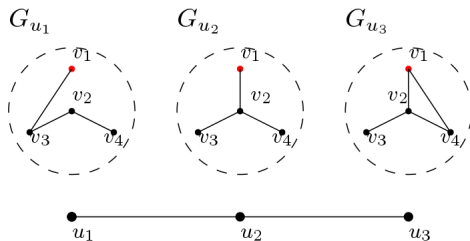
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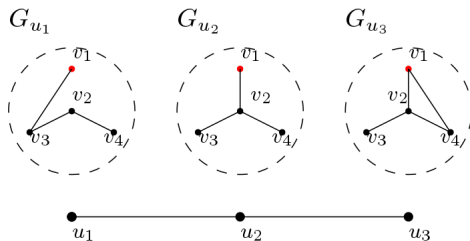
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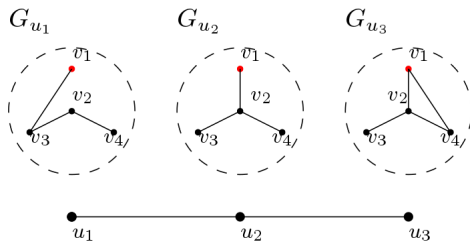
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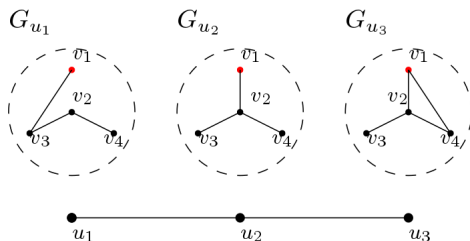
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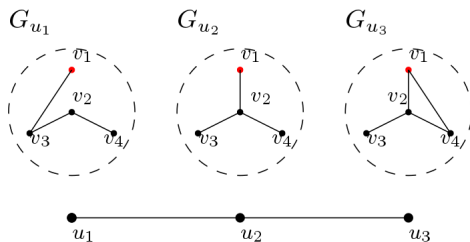
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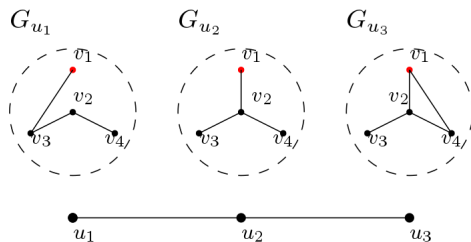
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- **Wrong** to use GSP on big ambient graph containing all G_{u_i} s.

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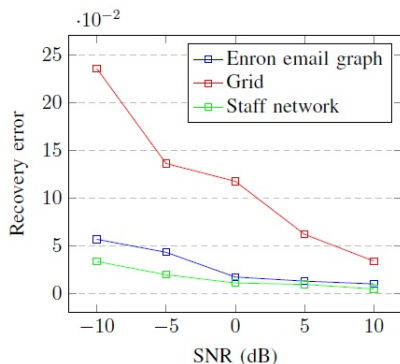
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- Recovery error:

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Graphs evolve according to model in [4] (applications in social networks, biological neuron networks, etc.).

[4] J. Ito and K. Kaneko, "Spontaneous structure formation in a network of chaotic units with variable connection strengths," *Phys. Rev. Letts.*, vol. 88, no. 2, p. 028701, 2002.

Outline

- 1 Generalized Graph Signals and \mathcal{F} -Transform
- 2 Sampling Theorem
- 3 Filtering
- 4 Conclusion

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Future

- Framework applicable for square integrable **graph stochastic processes**: for each $v \in V$, $X(v, t, \omega) \in L^2([0, T] \times \Omega, \mathcal{F}, \mathbb{P})$.
- Notions of stationarity can be defined w.r.t. the shift operators $A_G \otimes \text{Id}$, $\text{Id} \otimes A$ and $A_G \otimes A$ similar to [5,6].
- “Strict” and “weak” strong and wide-sense stationarity.
- Other high dimensional extensions: simplicial complexes [7] and hypergraphs [8].

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Acknowledgments

Singapore Ministry of Education Academic Research Fund Tier 2 grant
MOE2018-T2-2-019

Thank you!

<http://www.ntu.edu.sg/home/wptay/>



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